

Power System - 2

Book:- Steven Son
- Nagrath Kothari

- Standard book solved examples.
- IES mains solved problem.
- W.B. | IES previous year
- Gate previous year

--- Bhupendra Singh sir

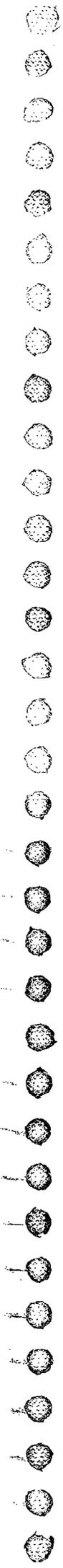
Topics:

For Gate
5 to 8

For ESE
Mains (MIMP)

- ① Fault
- ② E.D.
- ③ Load flow
- ④ Stability

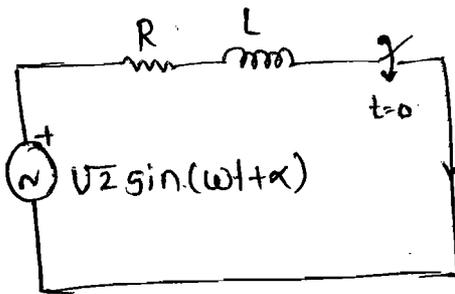
"No Selection, Without Revision"



Power Analysis of AC Circuit:

o AC Circuit:

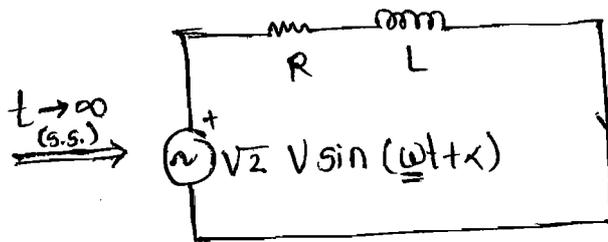
⇒ A circuit which is in steady state corresponding to a given sinusoidal excitation is called AC circuit.



Sinusoidal exponential

$$i(t) = i_{SS} + i_{TR}$$

--- Not an AC circuit.



Response freq. is same as the source freq.

$$i(t) = \sqrt{2} \cdot I \sin(\omega t + \beta)$$

--- An AC circuit

- Steady state response nature depends upon the source.
- Transient response nature depends upon circuit itself.

• $i(t) = i_{SS} + i_{TR}$ --- for Non-AC circuit

$$i(t) = \sqrt{2} \cdot I \sin(\omega t + \beta) + A e^{-t/\tau}$$

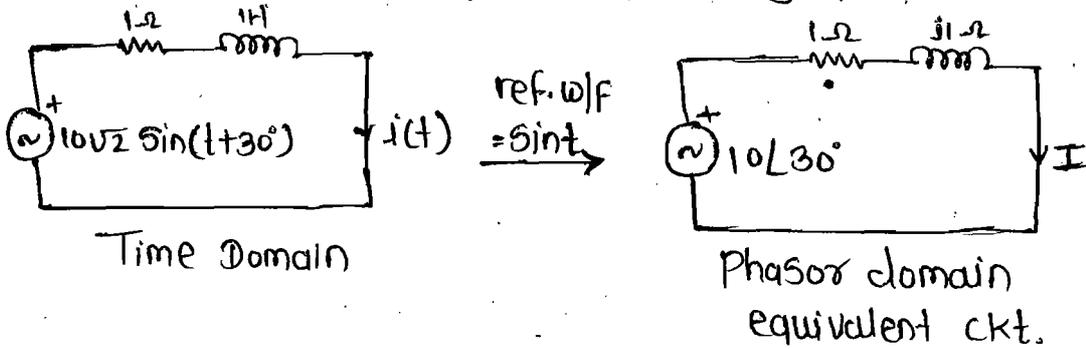
∴ Responses are Non-sinusoidal

• $i(t) = \sqrt{2} \cdot I \sin(\omega t + \beta)$ ---- for AC circuit.

∴ Response are sinusoidal.

⇒ All the responses of an AC ckt. are sinusoids with freq. equal to the source freq.

⇒ The magnitude (RMS Value) and phase of a response in an AC circuit is computed using phasor technique.



• $I = \frac{10\angle 30^\circ}{1+j1}$ --- phasor form

$I = \frac{10}{\sqrt{2}} \angle -15^\circ$

Time domain	→	R	L	C
Phasor	→	R	$j\omega L$	$\frac{1}{j\omega C}$
Freq.	→	R	sL	$\frac{1}{sC}$

• $i(t) = 10 \sin(t - 15^\circ)$ --- time domain.

$v_L(t) = 10 \sin(t + 75^\circ)$ ← $V_L = \frac{10}{\sqrt{2}} \angle 75^\circ$
 $= \left[\frac{j1}{1+j1} 10\angle 30^\circ \right]$

⊙ Power Calculation:

⇒ Complex power absorbed by AC ckt. / AC ckt. element:- (Fig ⊙)

$S = VI^* = P + jQ$

Where,

P = Active Power / Avg. power / Useful power
 Absorbed by AC ckt. / AC ckt. element (Watt)

ϕ = Reactive power / lagging VAR absorbed by AC circuit / AC ckt. element (VAR).

$P > 0$: ckt / ckt element absorbed Active power

$P < 0$: ckt / ckt. element delivers Active power.

$Q > 0$: ckt. / ckt. element absorbed Reactive power. (S)

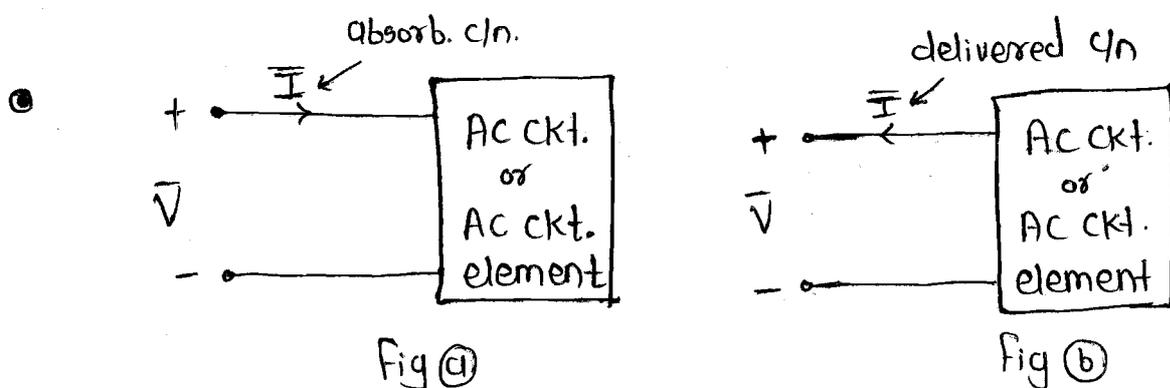
ckt / ckt. element absorbed Lagging VAR (S)

ckt. / ckt. element delivers Leading VAR

$\phi < 0$: ckt. / ckt. element delivers reactive power (S)

ckt. / ckt. element delivers lagging VAR (S)

ckt. / ckt. element leading VAR (absorbed)



⇒ Complex power delivered by AC ckt. / AC ckt. element :- (Fig (b))

$$S = VI^* = P + jQ$$

where,

P = Active power delivered by AC ckt. / AC ckt. element

Q = Reactive power / lagging VAR delivered by AC ckt. / AC ckt. element.

$P > 0$: ckt. delivers active power

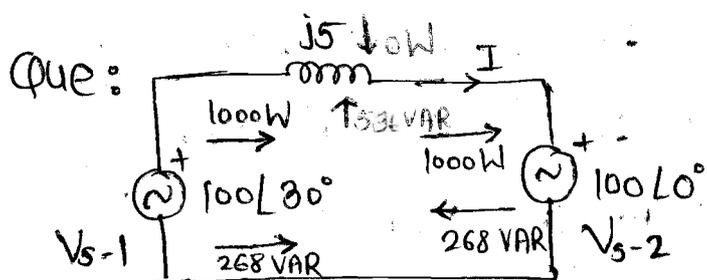
$P < 0$: ckt. absorbs Active power.

$\phi > 0$: ckt. delivers reactive power.

ckt. delivers lagging VAR / absorbed lead VAR.

$\phi < 0$: ckt. absorbed reactive power.

ckt. deliver absorbed lagging VAR / delivered lead VAR.



• Pure L & C absorbs 0W
in AC condition.

• L absorbs Reactive power

• C delivers Reactive power

Solⁿ:

$$I = \frac{100 \angle 30^\circ - 100 \angle 0^\circ}{j5}$$

$$I = 10.35 \angle 15^\circ$$

• Complex power absorbed by $V_s - 2$

$$S = VI^*$$

$$= (100 \angle 0^\circ) \cdot (10.35 \angle 15^\circ)^*$$

$$= (100 \angle 0^\circ) \cdot (10.35 \angle -15^\circ)$$

$$S = 1000 - j268$$

\therefore Vtg. source absorbs 1000W & delivers 268 VAR.

- Complex Power delivered by $V_s - 1$

$$S = VI^*$$

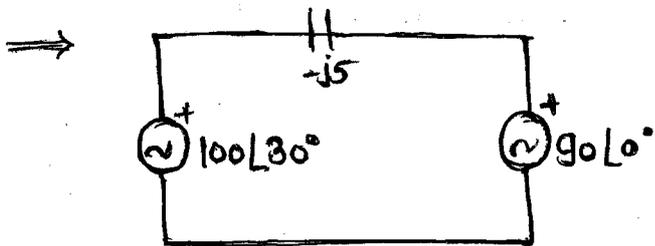
$$= (100 \angle 30^\circ) (10.35 \angle 75^\circ)^*$$

$$S = 1000 + j268$$

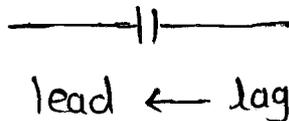
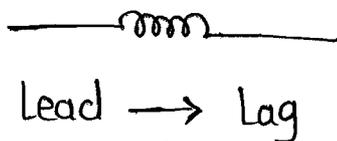
∴ Vtg. source - 1 delivers 1000W & delivers 268 VAR.

⊛ Note :

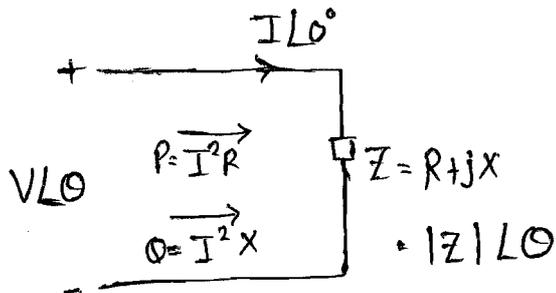
In power system, Active Power always flows from leading vtg. source towards lagging vtg. source, whereas, reactive power generally flows from high vtg. magnitude towards low vtg. magnitude.



In power s/m. ckt. in series branch always inductor & in parallel branch always capacitor.



⊙



$$Z = R + jX = \begin{matrix} X +ve = L \\ X -ve = C \end{matrix}$$

$$Y = G + jB = \begin{matrix} B +ve = C \\ B -ve = L \end{matrix}$$

$$Y = G + jB = \begin{matrix} B +ve = C \\ B -ve = L \end{matrix}$$

$$B -ve = L$$

$$|Z| = \sqrt{R^2 + X^2}$$

$$\theta = \tan^{-1}(X/R)$$

⊙ Complex power abs. by $Z = R + jX$

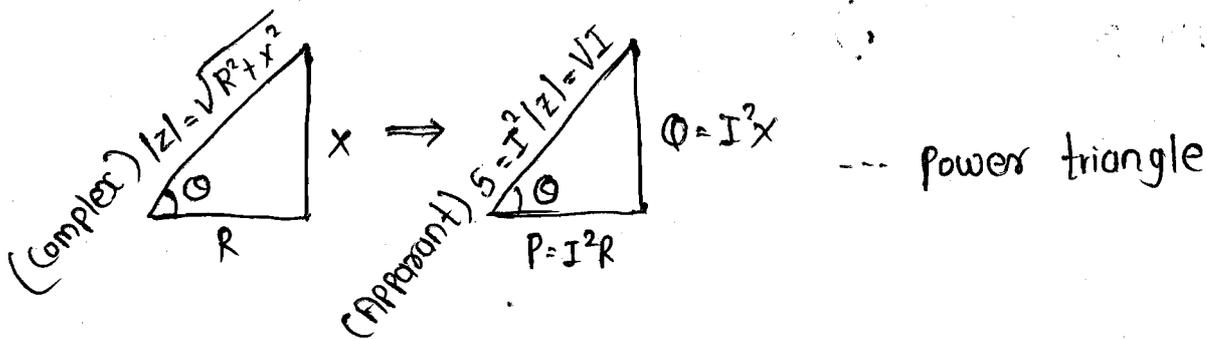
$$S = (V \angle \theta) (I \angle 0^\circ)^* = P + jQ = VI \angle \theta$$

(Active) $P = VI \cos \theta = VI \frac{R}{|Z|} = I^2 R$ --- (Real part of complex power)

(Reactive) $Q = VI \sin \theta = VI \frac{X}{|Z|} = I^2 X$ --- (Imag. part of complex power)

⊙ Apparent power:

$$S = I^2 |Z| = VI \text{ --- (magnitude of complex power)}$$



⊙ Power factor: $\cos \theta = \frac{P}{S} = \frac{\text{Active Power}}{\text{Apparent Power}}$ --- P.F.

$$\cos \theta = \cos \tan^{-1}\left(\frac{Q}{P}\right) \text{ --- m/c}$$

θ = angle betⁿ vtg. phasor & c/n phasor

- Resistance: It is the real part of impedance.

- Reactance: It is the imaginary part of impedance.

$R \geq 0 \rightarrow P \geq 0 \Rightarrow Z = R + jX$: cant delivered
Active power

⊙ $X > 0$ (Inductive Impedance)

- Inductive impedance absorbed Rea. power
- Inductive impedance absorbed Lag. VAR
- Inductive impedance del. lead. VAR.

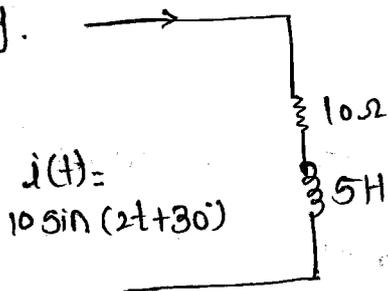
$X = 0$ (Resistive Impedance)

- $\phi = 0$

$X < 0$ (Capacitive Impedance)

- capacitive impedance del. Reactive power
- capacitive impedance del. Lag. VAR
- capacitive impedance absorbed lead. VAR.

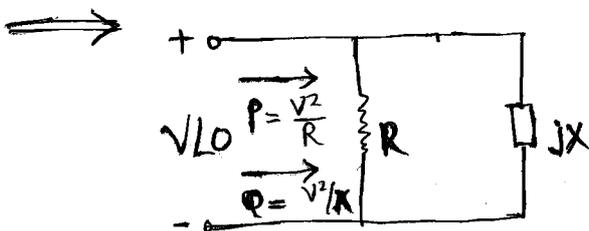
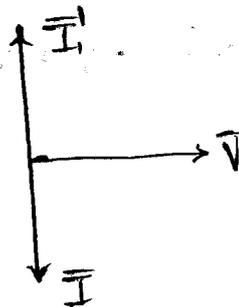
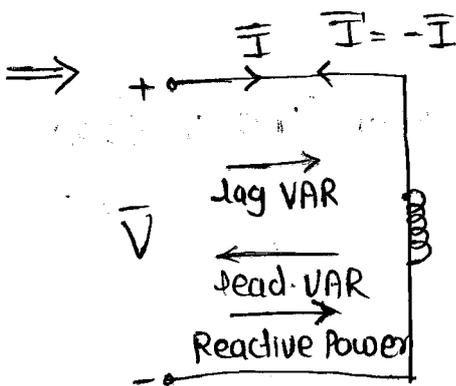
e.g.



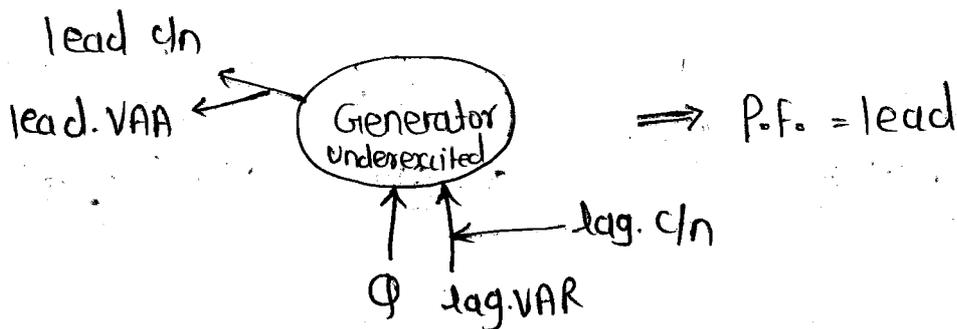
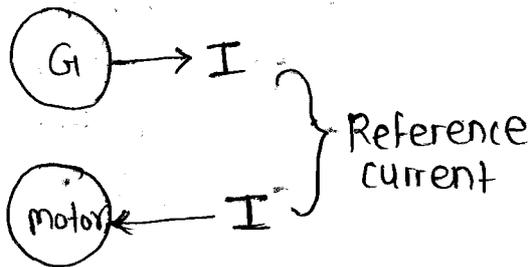
solⁿ:

$P = I^2 R = \left(\frac{10}{\sqrt{2}}\right)^2 \cdot 10 \text{ Watt}$

$Q = I^2 X = \left(\frac{10}{\sqrt{2}}\right)^2 \cdot (2 \times 5) \text{ VAR}$



• Significance of Reactive Power:



• Flux requirement depends upon operating voltage.

Balance 3- ϕ System |

9/06/2021
lec-2

Concept of phase Sequence

\Rightarrow A polyphase system is said to be balance if

① The magn. of corresponding quantities are equal in each phase.

② The phase difference betⁿ the corresponding quantities is given by,

$$\theta = \frac{360^\circ}{n} ; n \neq 2$$

$$= 90 ; n = 2$$

$$= \frac{360}{3} ; n = 3 \quad \dots \text{for } 3\text{-}\phi \text{ s/m}$$

Que. Current in two phases of two phase s/m is given below.

$$i_a = \sqrt{2} I \cos(\omega t - \phi_1)$$

$$i_b = \sqrt{2} I \sin(\omega t - \phi_2)$$

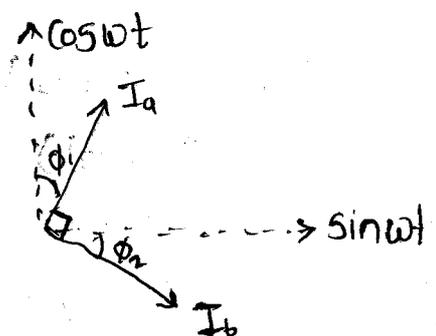
Find the relationship betⁿ ϕ_1 & ϕ_2 , so that the s/m is balance.

Solⁿ: leading \rightarrow +ve \Rightarrow Anticlockwise

$\cos \omega t$ leads
 $\sin \omega t$ by 90°

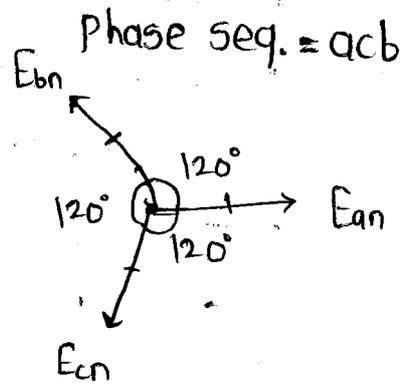
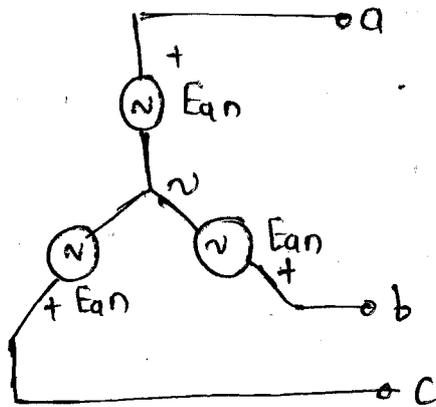
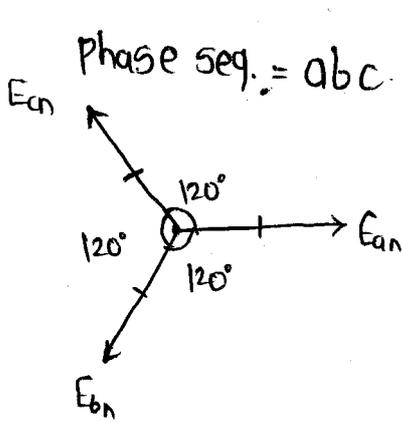
Lagging \rightarrow -ve \Rightarrow clockwise

$$\boxed{\therefore \phi_1 = \phi_2}$$

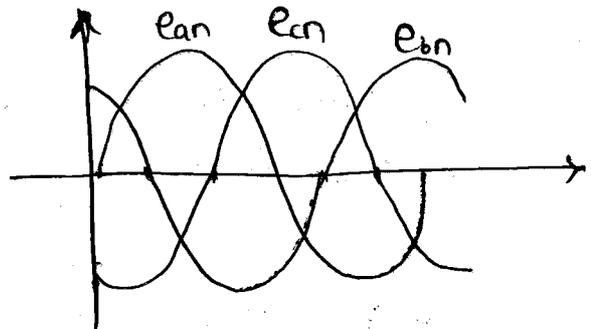
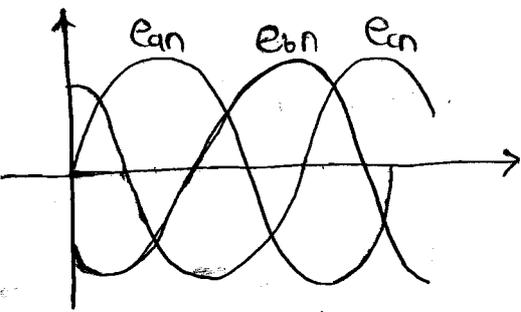


⊙ For 3- ϕ System:

Consider, a balance 3- ϕ (Ideal) Voltage Source. :
 ↓
 No impedance



⇒ Both phasor dia. is represent balance condition but they do differ phase sequence.

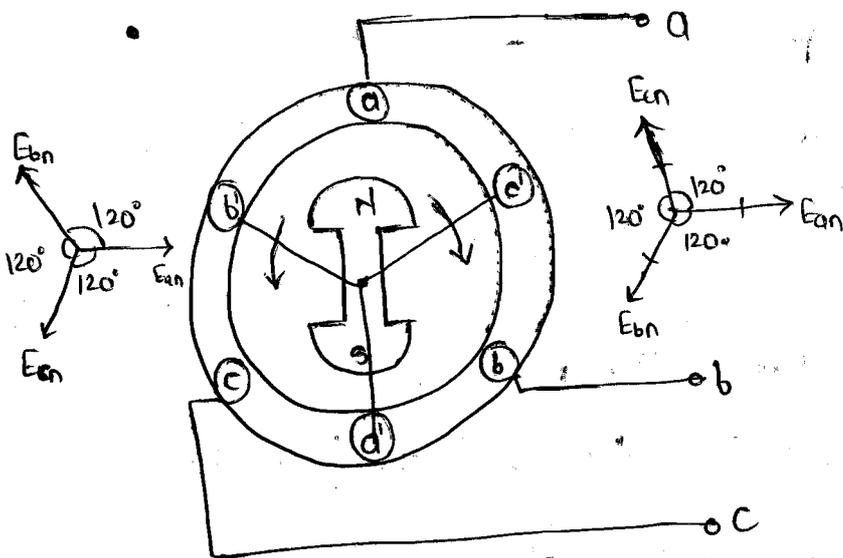
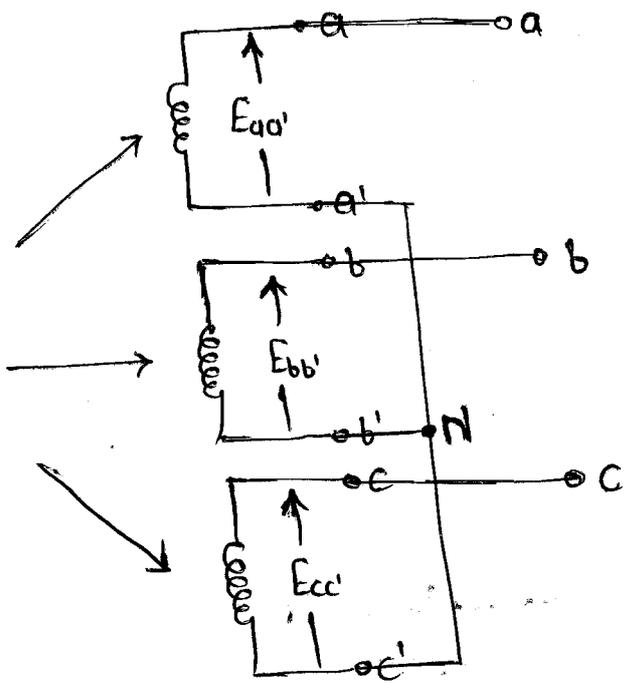


⊙ Phase sequence :

Phase sequence is defined as the order in which the phases attained their maximum value.

⇒ 3- ϕ (Ideal) voltage source is ckt. equivalent of a (Ideal) synchronous machine.

Identical winding
in all three phases
to produce equivalent
magnitude of a
voltage in all 3- ϕ 's.



$$\phi_e = \frac{P}{2} \phi_m$$

⊙ Note:

- ① Only two type of phase sequence (abc & acb) is possible in a 3- ϕ system.
- ② The phase sequence can be reverse by reversing the rotation of rotor, but practically doing it is not possible.
- ③ phase sequence cannot be reverse by reversing the field excitation.